

Mechatronic Systems and Control

Editor-in-Chief
 Prof. Clarence W. de Silva
 University of British Columbia, Canada

Frequency: 4 issues per year

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Scope

This international journal publishes both theoretical and application-oriented papers on various aspects of mechatronic systems, modelling, design, conventional and intelligent control, and intelligent systems. Application areas of mechatronics may include robotics, transportation, energy systems, manufacturing, sensors, actuators, and automation. Techniques of artificial intelligence may include soft computing (fuzzy logic, neural networks, genetic algorithms/evolutionary computing, probabilistic methods, etc.). Techniques may cover frequency and time domains, linear and nonlinear systems, and deterministic and stochastic processes. Hybrid techniques of mechatronics that combine conventional and intelligent methods are also included.

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University of Guelph, Canada

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Scope

First published in 1986, the International Journal of Robotics and Automation was one of the inaugural publications in the field of robotics. This journal covers contemporary developments in theory, design, and applications focused on all areas of robotics and automation systems, including new methods of machine learning, pattern recognition, biologically inspired evolutionary algorithms, fuzzy and neural networks in robotics and automation systems, computer vision, autonomous robots, human-robot interaction, microrobotics, medical robotics, mobile robots, biomechatronic systems, assistive technology, autonomous design of robotic systems, sensors, communication, and signal processing.

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