

Dong Won Kim - Curriculum Vitae

Address: 253 Yong Hyun-Dong, Nam-Ku, Incheon, South Korea 402-752

Website: <http://dwnkim.egloos.com/>

E-mail: dwnkim@inhac.ac.kr , dongwon.kim25@gmail.com

Phone: +82-10-4400-3689

Selected Publications and Presentations

BOOK CHAPTERS

Dongwon Kim, Gwi-Tae Park, *Advanced Humanoid Robot Based on the Evolutionary Inductive Self-organizing Network*, Humanoid Robots-New Developments, pp. 449-466, 2007.

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PATENTS

1. **Dong-Won Kim**, Sung-Hoe Huh, and Gwi-Tae Park, "Method for Speed Control of AC Motor Using the Radial Basis Function Network Observer," Korea Patent 10-2005-0008384, January 29, 2005,
2. **Dong-Won Kim**, and Gwi-Tae Park, "Method for controlling pose of robot with using neural network, Recording medium thereof, Apparatus for controlling pose of robot with using neuron-network and Robot therewith," Korea Patent 10-2005-0136357, December 31, 2005
3. **Dong-Won Kim**, and Gwi-Tae Park, "Method for designing walking control system of walking robot and Recording medium thereof, Apparatus for designing walking control system of walking robot and Robot thereby," Korea Patent 10-0757514, September 4, 2007

PROJECT

- 1. Title:** Development of Intelligent Speed Controller for Induction Motor Using RBFN
Support from: Korea Electrical Engineering & Science Research Institute
Period: 2003. 12. 01 ~ 2004. 11. 30
- 2. Title:** Study on the parameter optimization of RBFN using genetic algorithm and its application
Support from: Korea University
Period: 2004. 03. 01 ~ 2005. 02. 28
- 3. Title:** Tele-Monitoring of diesel engine and development of monitoring software
Support from: Hyun-dai Heavy Industrial Company
Period: 2005. 03 ~ 2006. 02
- 4. Title:** A Study on the Walking Pattern Analysis and its Application to Intelligent Walking Control for Flexible Humanoid Robot-Moving
Support from: Korea Science and Engineering Foundation (KOSEF)
Period: 2005. 04 ~ 2007. 03
- 5. Title:** Autonomous environment recognition and walking intelligence humanoid-robot based on the neuro-fuzzy and soft computing
Support from: Korea Research Foundation (KRF)
Visit Place: UC-Berkeley hosted by Prof. Lotfi A. Zadeh
Period: 2008. 01 ~ 2008. 12